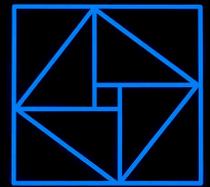


Hyper-gradient in bilevel optimization: efficient computation by Krylov subspace and enhanced investigation in reinforcement learning

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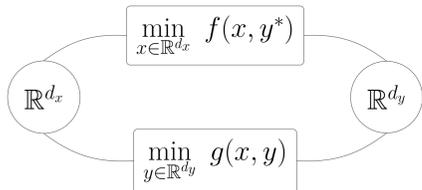
Bilevel optimization problem (BiO)

General form

$$\begin{aligned} \min_{x \in \mathbb{R}^{d_x}} \varphi(x) &:= f(x, y^*(x)) \\ \text{s. t. } y^*(x) &= \arg \min_{y \in \mathbb{R}^{d_y}} g(x, y) \end{aligned}$$

► $f, g: \mathbb{R}^{d_x} \times \mathbb{R}^{d_y} \rightarrow \mathbb{R}$, differentiable, g is **strongly convex**

The nested structure **couple**s the **upper level** and **lower level**



Approximate implicit differentiation (AID)

Hyper-gradient computation

$$\begin{aligned} \nabla \varphi(x) &= \nabla_x f(x, y^*(x)) + \nabla_x y^*(x)^\top \nabla_y f(x, y^*(x)) \\ &= \nabla_x f(x, y^*) - \nabla_{xy}^2 g(x, y^*) [\nabla_{yy}^2 g(x, y^*)]^{-1} \nabla_y f(x, y^*) \end{aligned}$$

Main difficulties

► Solving the lower-level problem to obtain $y^*(x)$

★ Approximating the **Hessian inverse vector product**

$$v^*(x) := [\nabla_{yy}^2 g(x, y^*(x))]^{-1} \nabla_y f(x, y^*(x))$$

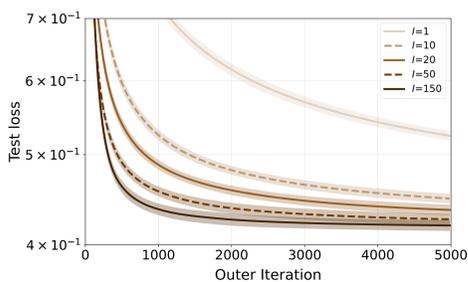
Vanilla update rule

$$1 \times : x^+ = x - \beta \left(\nabla_x f(x, y) - \nabla_{xy}^2 g(x, y) [\nabla_{yy}^2 g(x, y)]^{-1} \nabla_y f(x, y) \right)$$

$$N \times : y^+ = y - \alpha \nabla_y g(x, y)$$

Motivation

An observation



The more **accurate** v^* ,
the more **enhanced** descent!

Tackle v^* in BiO

Adhere to these two principles

► **Approximation**

► Subspace methods for **Approximation** [Yuan'14]

► **Amortization**

► Subspace iteration for **Amortization** [Yuan'95]

Geometric interpretation of AID: a subspace perspective

$$\begin{aligned} \min_{v \in \mathcal{S}_k} m_k(v) &:= \frac{1}{2} v^\top \nabla_{yy}^2 g(x_k, y_k) v - \nabla_y f(x_k, y_k)^\top v \\ \mathcal{S}_k = \mathbb{R}^{d_y} &\implies v_k = \nabla_{yy}^2 g(x_k, y_k)^{-1} \nabla_y f(x_k, y_k) := A_k^{-1} b_k \end{aligned}$$

Low-dimensional subspace?

Krylov subspace [Krylov'31] provides a good estimate for $A^{-1}b$ [Carmon and Duchi'18]

$$\mathcal{K}_N(A, b) := \text{span}\{b, Ab, A^2b, \dots, A^{N-1}b\}$$

Dynamic Lanczos process in BiO

Core principles

► Maintain an **orthogonal basis** $Q_j = [q_1, \dots, q_j]$ to construct $\mathcal{S}_k \approx \mathcal{K}_j(A_j, b_j)$

► Keep the (approximate) projection matrix T_j **tridiagonal**

► Dynamically solve quadratic subproblems:

$$v_k := \arg \min_{v \in \mathcal{S}_k} m_k(v) := \frac{1}{2} v^\top A_k v - b_k^\top v$$

Adapt standard Lanczos process in BiO

$$\begin{aligned} u_j &= A_j q_j - \beta_j q_{j-1}, & \alpha_j &= q_j^\top u_j & \omega_j &= u_j - \alpha_j q_j & T_j &= \begin{pmatrix} & & & 0 \\ & & & \beta_j \\ & & & \alpha_j \\ & & 0 & \beta_j \\ & & & \alpha_j \end{pmatrix} \\ \beta_{j+1} &= \|\omega_j\| & q_{j+1} &= \omega_j / \beta_{j+1} \end{aligned}$$

Lanczos process is inherently unstable [Paige'80; Meurant and Strakoš'06]

Two "Res" strategies: LancBiO

Restart mechanism

► Restart subspaces each m steps

► Mitigate the accumulation of difference among $\{A_1, \dots, A_k\}$

Residual minimization

► Minimal residual subproblems

$$\min_{\Delta v \in \mathcal{S}_k} \|(b_k - A_k \bar{v}) - A_k \Delta v\|^2$$

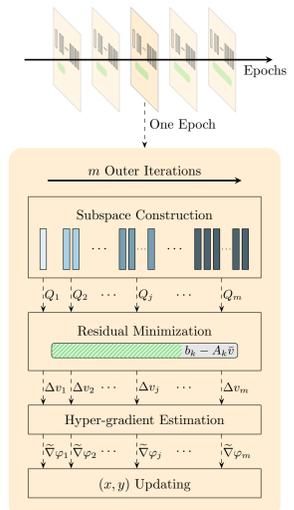
► Correct current \bar{v} , $v_k = \bar{v} + \Delta v_k$

► Collect **historical information**

Computational complexity

⊙ Low-dimensional subproblems

⊙ No cost of Hessian projection



Theoretical analysis and numerical experiment

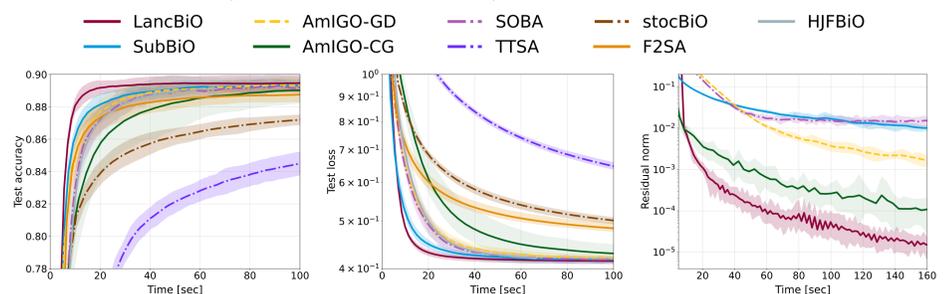
Theorem

With appropriate step sizes θ for y and λ for x , the iterates $\{x_k\}$ satisfy

$$\frac{m}{K(m - m_0)} \sum_{k=0, (k \bmod m) > m_0}^K \|\nabla \varphi(x_k)\|^2 = \mathcal{O}\left(\frac{m\lambda^{-1}}{K(m - m_0)}\right)$$

where m is the subspace dimension and $m_0 \sim \Omega(\log m)$

Test on MNIST (pollution rate=0.8)



Bilevel reinforcement learning (BiRL)

Parameterized MDP $\mathcal{M}_\tau(x) = (\mathcal{S}, \mathcal{A}, P, r(x), \gamma, \tau)$

► Soft value functions $V_s^\pi(x) = \mathbb{E}[\sum_{t=0}^{\infty} \gamma^t (r_{s_t a_t}(x) + \tau h(\pi_{s_t})) \mid s_0 = s, \pi, \mathcal{M}_\tau(x)]$

► $h(\pi_s) = -\sum_a \pi_{sa} \log \pi_{sa}$ and $V_{\mathcal{M}_\tau(x)}^\pi(\rho) = \mathbb{E}_{s \sim \rho}[V_s^\pi(x)]$ with the initial distribution ρ

Problem formulation

$$\begin{aligned} \min_{x \in \mathbb{R}^n} \phi(x) &:= f(x, \pi^*(x)) \\ \text{s. t. } \pi^*(x) &= \arg \min_{\pi} -V_{\mathcal{M}_\tau(x)}^\pi(\rho) \end{aligned}$$

where $f(x, \pi) = \mathbb{E}_{d_t \sim \rho(d, \pi)}[l(d_1, d_2, \dots, d_T; x)]$

Main difficulty

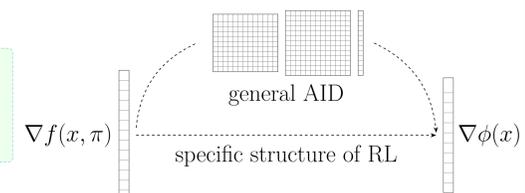
► The lower-level problem is inherently **non-convex** [Agarwal et al.'20; Lan'23 MP]

Does hyper-gradient $\nabla \phi(x)$ exist?

Develop hyper-gradient in BiRL

Estimate via sampling first-order information

$$\begin{aligned} \nabla \phi(x) &= \mathbb{E}_{d_t} [\nabla l(d; x)] \\ &+ \tau^{-1} \mathbb{E}_{d_t} \left[l(d; x) \left(\sum_i \sum_t \nabla (Q_{s_i a_i}^*(x) - V_{s_i}^*(x)) \right) \right] \end{aligned}$$



Comparison of convergence results among BiRL methods

Algorithm	Deter. or Stoch.	Conv. Rate	Inner Iter.	Oracle
PARL [Chakraborty et al.'24 ICLR]	Deter.	$\mathcal{O}(\epsilon^{-1})$	$\mathcal{O}(\log \epsilon^{-1})$	1st+2nd
PBRL [Shen et al.'24 ICML]	Deter.	$\mathcal{O}(\lambda \epsilon^{-1})$	$\mathcal{O}(\log \lambda^2 \epsilon^{-1})$	1st
HPGD [Thoma et al.'24 NeurIPS]	Stoch.	$\mathcal{O}(\epsilon^{-2})$	$\mathcal{O}(\log \epsilon^{-1})$	1st
M-SoBiRL	Deter.	$\mathcal{O}(\epsilon^{-1})$	$\mathcal{O}(1)$	1st
SoBiRL	Deter.	$\mathcal{O}(\epsilon^{-1})$	$\mathcal{O}(\log \epsilon^{-1})$	1st
Stoc-SoBiRL	Stoch.	$\tilde{\mathcal{O}}(\epsilon^{-1.5})$	$\mathcal{O}(\log \epsilon^{-1})$	1st

References

- Yan Yang, Bin Gao, Ya-xiang Yuan. *LancBiO: dynamic Lanczos-aided bilevel optimization via Krylov subspace*. ICLR (2025)
- Yan Yang, Bin Gao, Ya-xiang Yuan. *Bilevel reinforcement learning via the development of hyper-gradient without lower-level convexity*. AISTATS (2025)
- Code and more experiments are publicly available from <https://github.com/UCAS-YanYang>